

Stokes Theorem

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Green's Theorem

Let D be an open domain in the plane \mathbb{R}^2 (think of \mathbb{R}^2 as xy plane in \mathbb{R}^3)

Suppose \vec{F} is a vector field defined on D
ie $\vec{F} = P\hat{i} + Q\hat{j} + R\hat{k}$ (will generalize to \mathbb{R}^2)
and C is a simple closed curve in D s.t.

$$\text{int}(C) \in D$$

Green's Thm (Classical Form)

$$\int_C \vec{F} \cdot d\vec{r} = \iint_{\text{int}(C)} \left(\frac{\partial Q}{\partial x} - \frac{\partial P}{\partial y} \right) dA$$

Green's Thm (Rewritten)

Think of $\text{int}(C)$ as a surface in \mathbb{R}^3 with orientation upward (in z -dir.)
Let's consider a vector field \vec{g} with $\vec{g} \cdot \hat{k} = \hat{k}$ -component of \vec{g} .

$$= \frac{\partial Q}{\partial x} - \frac{\partial P}{\partial y}$$

Notice: $C = \partial(\text{int}(C))$
↑ "boundary"

$$\int_{\partial(\text{int}(C))} \vec{F} \cdot d\vec{r} = \iint_{\text{int}(C)} \vec{g} \cdot d\vec{\sigma}$$

Surface integral

Note: For $\text{int}(C)$ viewed as a surface in \mathbb{R}^3 , its normal vector \vec{n} is \hat{k}

$$\Rightarrow \iint_{\text{int}(C)} \vec{g} \cdot d\vec{\sigma} \text{ depends only on } \hat{k} \text{ component of } \vec{g}$$

Stokes Thm

Let D be a domain in \mathbb{R}^3 .

Let Σ be a surface in D .

Suppose $\vec{F} = P\hat{i} + Q\hat{j} + R\hat{k}$ is a vector field defined on D , differentiable

Then for an appropriate vector field \vec{g} (determined by \vec{F}) with $\hat{k} \cdot \vec{g} = \frac{\partial Q}{\partial x} - \frac{\partial P}{\partial y}$

We have:

$$\int_{\partial(\Sigma)} \vec{F} \cdot d\vec{r} = \iint_{\Sigma} \vec{g} \cdot d\vec{\sigma} \quad \text{with consistent orientations via RHR}$$

Remark

the RHS depends on Σ , while LHS depends only on $\partial\Sigma$

eg $\Sigma_1 =$ northern hemisphere of unit sphere

$\Sigma_2 =$ southern hemisphere of unit sphere

then $\partial\Sigma_1 = \partial\Sigma_2 =$ equator

therefore

$$\iint_{\Sigma_1} \vec{g} \cdot d\vec{\sigma} = \iint_{\Sigma_2} \vec{g} \cdot d\vec{\sigma}$$

caveat may be \pm depending on orientations

For $\Sigma_1 = \dots$

caveat may be \pm depending on orientations
 For $(+)$, need both upward or both downward

This is similar to the statement that if C is a curve from P to Q , and $\vec{g} = \nabla F$, then

$$\int_C \vec{g} \cdot d\vec{r} = F(Q) - F(P)$$

\rightarrow so the LHS depends only on the endpoints of C , (i.e. $\partial(C)$) and not a particular path b/w them

What is \vec{g} in terms of \vec{r} ?

Recall

$$\vec{r} = P\vec{i} + Q\vec{j} + R\vec{k}$$

$$\vec{r} \cdot \vec{g} = \frac{\partial Q}{\partial x} - \frac{\partial P}{\partial y}$$

Idea Pretend we have a "vector":

$$\nabla = \frac{\partial}{\partial x} \vec{i} + \frac{\partial}{\partial y} \vec{j} + \frac{\partial}{\partial z} \vec{k}$$

$$\nabla \times \vec{r} = \left(\frac{\partial R}{\partial y} - \frac{\partial Q}{\partial z} \right) \vec{i} + \left(\frac{\partial P}{\partial z} - \frac{\partial R}{\partial x} \right) \vec{j} + \left(\frac{\partial Q}{\partial x} - \frac{\partial P}{\partial y} \right) \vec{k}$$

$$= \vec{g}$$

this is the \vec{g} in terms of \vec{r} , making Stokes Thm true

Recall for $\vec{r} = P\vec{i} + Q\vec{j}$ in the plane, we defined

$$\text{curl } \vec{r} = \frac{\partial Q}{\partial x} - \frac{\partial P}{\partial y} \quad \leftarrow \text{scalar field}$$

$\leftarrow \vec{k}$ -component of $\text{curl } \vec{r}$ for \vec{r} in xy plane

In fact the usual defn of curl is for 3-dim vector fields and produces another vector field, it is

$$\nabla \times \vec{F} = \text{curl } \vec{F}$$

Statement of Stokes

For a vector field \vec{F} , surface Σ , all in some domain \mathbb{R}^3 ,

$$\int_{\partial \Sigma} \vec{F} \cdot d\vec{r} = \iint_{\Sigma} \text{curl } \vec{F} \cdot d\vec{\sigma}$$

Let $\Sigma =$ disc of radius r around $P \in \mathbb{R}^3$, parallel to xy -plane

eg, if $P = (2, 3, 4)$, then this disc lies in the plane $z=4$

Let $P = (x_0, y_0, z_0)$

$$\int_{\partial \Sigma} \vec{F} \cdot d\vec{r} = \iint_{\Sigma} \text{curl } \vec{F} \cdot d\vec{\sigma}$$

$$= \iint_{\Sigma} (\text{curl } \vec{F} \cdot \vec{k}) dA$$

$$\approx (\text{curl } \vec{F}(P) \cdot \vec{k}) \text{area}(\Sigma)$$

\hookrightarrow As $r \rightarrow 0$, the \approx gets better

$$\Rightarrow \text{curl } \vec{F}(P) \cdot \vec{k} = \lim_{r \rightarrow 0} \frac{\int_{\partial \Sigma} \vec{F} \cdot d\vec{r}}{\text{area}(\Sigma)}$$

Recall what about Σ gives the \hat{k} -component of curl at P?

bc Σ is parallel to xy-plane

bc Σ is a little disc around P
 $\Rightarrow \partial \Sigma$ is a circle around P

Rewrite

Let $C_r^{xy}(P)$ = circle of radius r and center P lying in a plane parallel to xy-plane

then for any continuously differentiable vector field \vec{F}

$$\hat{k} \cdot \text{curl } \vec{F}(P) = \lim_{r \rightarrow 0} \frac{\int_{C_r^{xy}(P)} \vec{F} \cdot d\vec{r}}{\pi r^2}$$

"curl as circulation"

Simil let $C_r^{yz}(P)$ = circle of radius r and center P lying in a plane parallel to yz-plane

$P = (x_0, y_0, z_0)$, then

$$C_r^{yz}(P) = \left\{ (x, y, z) \in \mathbb{R}^3 \mid \begin{array}{l} x = x_0 \\ (y - y_0)^2 + (z - z_0)^2 = r^2 \end{array} \right\}$$

$$\text{Then } \hat{i} \cdot \text{curl } \vec{F}(P) = \lim_{r \rightarrow 0} \frac{\int_{C_r^{yz}(P)} \vec{F} \cdot d\vec{r}}{\pi r^2}$$

Similar

$$\hat{j} \cdot \text{curl } \vec{F}(P) = \lim_{r \rightarrow 0} \frac{\int_{C_r^{xz}(P)} \vec{F} \cdot d\vec{r}}{\pi r^2}$$

Theorem $\text{curl}(\nabla F) = 0$

Proof 1

write $\nabla F = \left(\frac{\partial F}{\partial x}, \frac{\partial F}{\partial y}, \frac{\partial F}{\partial z} \right)$ then $\text{curl}(\nabla F)$ using the fact that mixed partials commute

Heuristic if we think of $\vec{\nabla}$ as a vector:

∇F is like $\vec{\nabla}$ times scalar F

$\Rightarrow \nabla F$ is "parallel" to $\vec{\nabla}$

$\Rightarrow \vec{\nabla} \times (\vec{\nabla} F) = 0$

Proof 2

path integral of ∇F is path-ind (bc conservative)

$$\Rightarrow \int_C \nabla F \cdot d\vec{r} = 0 \text{ if } C \text{ a closed curve}$$

eg, for $C = C_r^{xy}(P), C_r^{yz}(P), C_r^{xz}(P)$

\Rightarrow each component of $\text{curl}(\nabla F)$ at any point P in the domain of F is

$$\lim_{r \rightarrow 0} \frac{0}{\pi r^2} = 0$$

domain of F is

$$\lim_{r \rightarrow 0} \frac{0}{\pi r^2} = 0$$

$$\Rightarrow \operatorname{curl}(\nabla F) = 0$$